# 전파 간섭계

2019.08.27 — 08.29 서울대학교 평창캠퍼스 2019 전파 여름학교

#### 권우진 Woojin Kwon





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## Radio observations

To achieve 1 arc-second resolution

at  $\lambda = 500$  nm: D ~ 10 cm at  $\lambda = 1$  mm : D ~ 200 m  $\theta \sim \lambda/D$ 

- Difficulties in building a big radio telescope:
  - 1. The required tracking accuracy  $\sim$  0/10 but the best mechanical tracking and pointing accuracy  $\sim$  1" due to
    - Gravitational sagging
    - Antenna deformations caused by differential solar heating
    - Wind gusts
  - 2. Surface accuracy ~ λ/20

#### What radio interferometers look like?

- Arrays: e.g., JVLA, SMA, NOEMA, ALMA
- Very Long Baseline Interferometers: e.g., KVN







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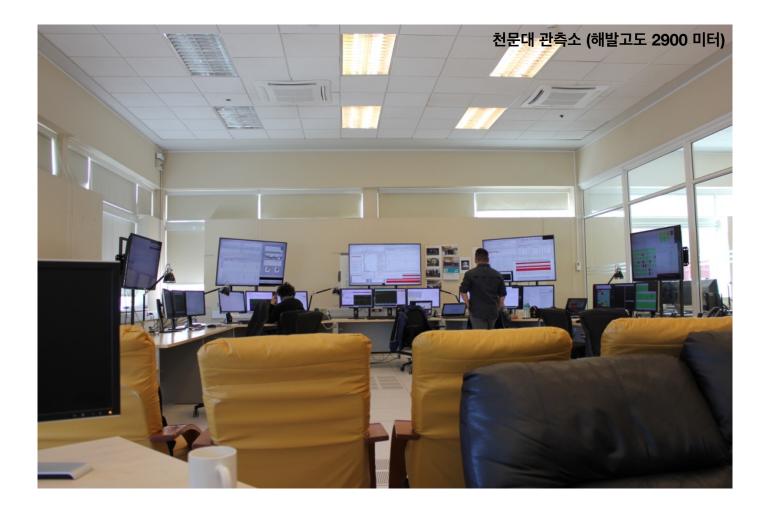


#### **ALMA** 인류 역사상 가장 규모가 큰 천문대



## **ALMA** 인류 역사상 가장 규모가 큰 천문대





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## References

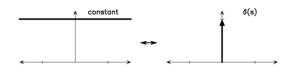
- Essential Radio Astronomy (3.7)
   J. J. Condon and S. M. Ransom, NRAO
   https://science.nrao.edu/opportunities/courses/era/
- Fundamentals of Radio Astronomy (ch. 5, 6)
   J. M. Marr, R. L. Snell, and S. E. Kurtz
- Tools of Radio Astronomy K. Rohlfs and T. L. Wilson
- Interferometry and Synthesis in Radio Astronomy
   A. Richard Thompson, James M. Moran, and George W. Swenson, Jr.
- Synthesis Imaging in Radio Astronomy
   Astronomical Society of the Pacific Conference Series (Volume 180)

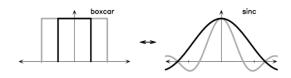


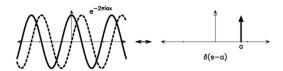
### Fourier transform

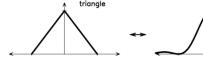
$$F(s) \equiv \int_{-\infty}^{\infty} f(x) e^{-2\pi i s x} dx,$$

$$f(x) \equiv \int_{-\infty}^{\infty} F(s) \ e^{2\pi i s x} \ ds,$$

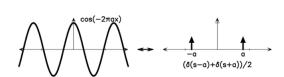


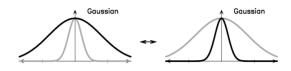












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## Fourier transform

$$F(s) \equiv \int_{-\infty}^{\infty} f(x) e^{-2\pi i s x} dx,$$

$$f(x) \equiv \int_{-\infty}^{\infty} F(s) e^{2\pi i s x} ds,$$

$$f(x) + g(x) \Leftrightarrow F(s) + G(s).$$

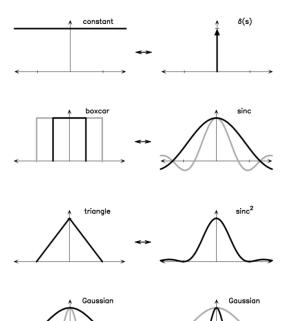
$$af(x) \Leftrightarrow aF(s).$$

$$f(x - a) \Leftrightarrow e^{-2\pi i a s} F(s).$$

$$f(ax) \Leftrightarrow \frac{F(s/a)}{|a|}.$$

$$f(x)\cos(2\pi\nu x) \Leftrightarrow \frac{1}{2}F(s-\nu) + \frac{1}{2}F(s+\nu).$$

 $\frac{df}{dx} \Leftrightarrow i2\pi s F(s).$ 

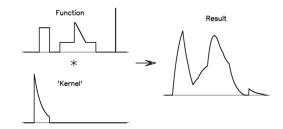


#### Convolution & Cross-correlation

Convolution

$$h(x) = f * g \equiv \int_{-\infty}^{\infty} f(u) g(x - u) du.$$

$$f * g \Leftrightarrow F \cdot G$$
. Convolution theorem



Cross-correlation

$$f \star g \equiv \int_{-\infty}^{\infty} f(u) g(u - x) \ du.$$
 
$$\boxed{f \star g \Leftrightarrow \overline{F} \cdot G.}$$
 Cross-correlation theorem

Auto-correlation

$$\boxed{f \star f \Leftrightarrow \overline{F} \cdot F = \left| F \right|^2.}$$
 Wiener-Khinchin theorem

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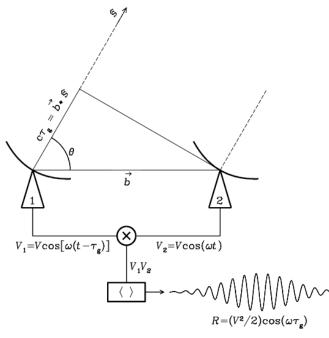
### FOV & $\theta_s$ of interferometers

- Optical telescopes: detectors with millions pixels
- Radio single dish antennas: one or a small number of receivers (e.g., TRAO SEQUOIA with 16 pixels)
- Interferometers:

e.g., ALMA 12 m antennas over 12 km in Band 6 ( $\sim$ 1.2 mm) FOV  $\sim \lambda/D \sim 20$ "

$$\theta_s \sim \lambda/(longest baseline) \sim 0.02"$$
  
==> 106 "pixels"

# Quasi-monochromatic 2-element interferometer

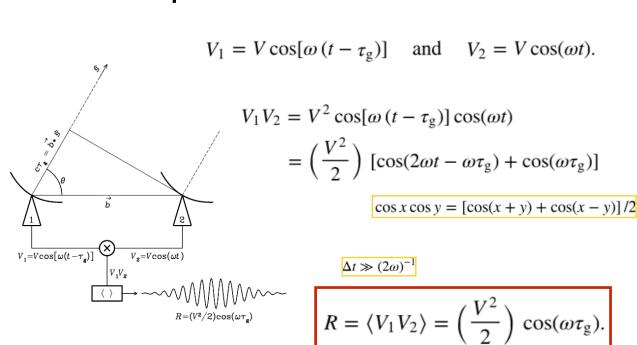


- "General" case!
- Quasi-monochromatic condition:  $\Delta \nu \ll 1/ au_{
  m g}$
- Correlator: multiply and time-average
- Geometric delay:  $\tau_{\rm g} = \frac{\vec{b} \cdot \hat{s}}{c}$

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## Output of correlator

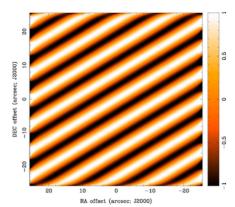


# Fringes

- Fringes: sinusoidal correlator output
- Fringe phase

$$\phi = \omega \tau_{\rm g} = \frac{\omega}{c} b \cos \theta$$

$$\left| \frac{d\phi}{d\theta} \right| = \frac{\omega}{c} b \sin \theta$$
$$= 2\pi \left( \frac{b \sin \theta}{\lambda} \right)$$



The **fringe period**  $\Delta \phi = 2\pi$  corresponds to an angular shift  $\Delta \theta = \lambda l (b \sin \theta)$ .

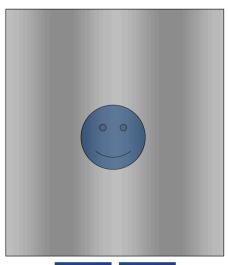
Depending on projected baselines Good image?

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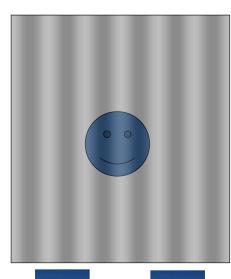
40

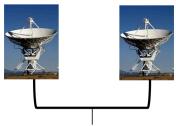
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## Sensitive Scales of Fringes

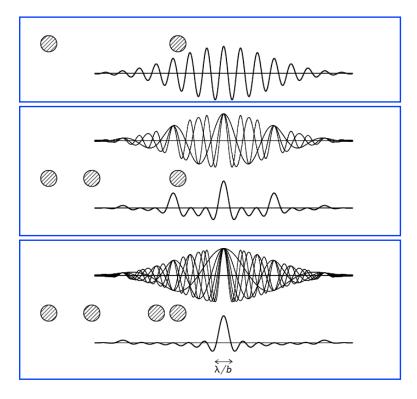








## More antennas better image



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## Complex correlator

- Slightly extended sources ( $I = I_E + I_O$ )
  - "cosine" correlator sensitive to even (inversion symmetric) structure
  - "sine" correlator sensitive to odd (anti-symmetric) structure

$$R_{c} = \int I(\hat{s}) \cos(2\pi\nu \vec{b} \cdot \hat{s}/c) d\Omega = \int I(\hat{s}) \cos(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

$$R_{s} = \int I(\hat{s}) \sin(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

Complex correlator: combination of cosine and sine correlators cf. Euler's formula  $e^{i\phi} = \cos \phi + i \sin \phi$ 

$$\mathcal{V} \equiv R_{\rm c} - iR_{\rm s}$$

$$\mathcal{V} = Ae^{-i\phi}$$

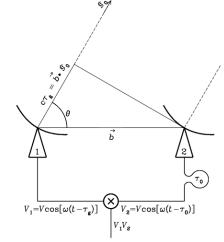
$$A = (R_c^2 + R_s^2)^{1/2}$$
$$\phi = \tan^{-1} (R_s/R_c)$$

bility 
$$\mathcal{V} \equiv R_{\rm c} - iR_{\rm s}$$
  $\mathcal{V} = Ae^{-i\phi}$  
$$\mathcal{V} = \int I(\hat{s}) \exp(-i2\pi \vec{b} \cdot \hat{s}/\lambda) \ d\Omega$$

## Bandwidth smearing

Quasi-monochromatic interferometers => interferometers with finite bandwidths and integration times

$$\begin{split} \mathcal{V} &= \int \left[ \int_{\nu_{c} - \Delta \nu/2}^{\nu_{c} + \Delta \nu/2} I_{\nu} \left( \hat{s} \right) \, \exp(-i2\pi \vec{b} \cdot \hat{s}/\lambda) \, d\nu \right] d\Omega \\ &= \int \left[ \int_{\nu_{c} - \Delta \nu/2}^{\nu_{c} + \Delta \nu/2} I_{\nu} \left( \hat{s} \right) \, \exp(-i2\pi \nu \tau_{g}) \, d\nu \right] d\Omega. \\ \mathcal{V} &\approx \int I_{\nu} \left( \hat{s} \right) \, \text{sinc} \, \left( \Delta \nu \, \tau_{g} \right) \, \exp(-i2\pi \nu_{c} \tau_{g}) d\Omega. \end{split}$$



Instrumental delay  $\tau_0$ to minimize the attenuation

$$|\tau_0 - \tau_g| \ll (\Delta \nu)^{-1}$$

$$\Delta \nu \, \Delta au_{
m g} \ll 1$$

$$|\tau_0 - \tau_{\rm g}| \ll (\Delta \nu)^{-1}$$
  $\Delta \nu \, \Delta \tau_{\rm g} \ll 1$   $\Delta \nu \, (b \sin \theta) \, \Delta \theta / c \ll 1$ 

$$c\tau_{\rm g} = \vec{b} \cdot \vec{s} = b \cos \theta$$
  $|c\Delta \tau_{\rm g}| = b \sin \theta \Delta \theta$ 

$$|c\Delta\tau_{\rm g}| = b\sin\theta\Delta\theta$$

$$\theta_{\rm s} \approx \lambda / (b \sin \theta)$$

$$\Delta \nu \ll \nu \frac{\theta_s}{\Delta \theta}$$

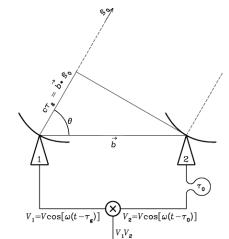
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# Bandwidth smearing

Quasi-monochromatic interferometers => interferometers with finite bandwidths and integration times

$$\begin{split} \mathcal{V} &= \int \left[ \int_{\nu_{\rm c} - \Delta \nu/2}^{\nu_{\rm c} + \Delta \nu/2} I_{\nu} \left( \hat{s} \right) \, \exp(-i2\pi \vec{b} \cdot \hat{s}/\lambda) \, d\nu \right] d\Omega \\ &= \int \left[ \int_{\nu_{\rm c} - \Delta \nu/2}^{\nu_{\rm c} + \Delta \nu/2} I_{\nu} \left( \hat{s} \right) \, \exp(-i2\pi \nu \tau_{\rm g}) \, d\nu \right] d\Omega. \\ \mathcal{V} &\approx \int I_{\nu} \left( \hat{s} \right) \, \text{sinc} \, \left( \Delta \nu \, \tau_{\rm g} \right) \, \exp(-i2\pi \nu_{\rm c} \tau_{\rm g}) d\Omega. \end{split}$$

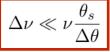


Instrumental delay  $\tau_0$ to minimize the attenuation

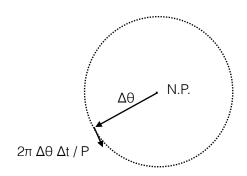
$$|\tau_0 - \tau_{\rm g}| \ll (\Delta t)$$

$$c\tau_{\rm g} = \vec{b} \cdot \vec{s} = b \, \vec{0}$$

$$\Delta \nu \ll \frac{\nu \theta_{\rm s}}{\Delta \theta} = \frac{1.5 \times 10^9 \text{ Hz} \cdot 4 \text{ arcsec}}{900 \text{ arcsec}} \approx 7 \text{ MHz}.$$



## Integration time smearing



$$P \approx 23^{\rm h}56^{\rm m}04^{\rm s} \approx 86164$$

$$\frac{2\pi\Delta\theta\Delta t}{P}\ll\theta_s$$

$$\Delta t \ll \frac{\theta_{\rm s}}{\Delta \theta} \cdot 1.37 \times 10^4 \text{ s}$$

$$\Delta t \ll \frac{\theta_s}{\Delta \theta} \cdot 1.37 \times 10^4 \text{ s} = \frac{4 \text{ arcsec}}{900 \text{ arcsec}} \cdot 1.37 \times 10^4 \text{ s} \approx 60 \text{ s}.$$

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## Visibility

- Now, assuming an interferometer with a negligible bandwidth attenuation
- Visibility: data of interferometers (Fourier transform of an image)

$$\mathcal{V} \approx \int I_{\nu}(\hat{s}) \sin((\Delta \nu \tau_{\rm g})) \exp(-i2\pi \nu_{\rm c} \tau_{\rm g}) d\Omega.$$

$$V \approx \int (A(\hat{s})I_{\nu}(\hat{s}) \exp(-i2\pi\nu\tau)d\Omega$$

$$= \int A(\hat{s})I_{\nu}(\hat{s}) \exp[-i2\pi\nu\left(\frac{\vec{b}\cdot\hat{s}}{c} - \tau_{i}\right)]d\Omega$$

$$= \exp[-i2\pi\nu \left(\frac{\vec{b}\cdot\hat{s_0}}{c} - \tau_i\right)] \int A(\hat{s})I_{\nu}(\hat{s})\exp[-i2\pi\nu \left(\frac{\vec{b}\cdot\hat{\sigma}}{c}\right)]d\Omega$$

$$V = \int A(\hat{s})I_{\nu}(\hat{s})\exp[-i2\pi\nu\left(\frac{\vec{b}\cdot\hat{\sigma}}{c}\right)]d\Omega$$

Steering antenna with an instrumental delay

$$\tau = \tau_g - \tau_i$$

Phase center so

$$\hat{s} = \hat{s_0} + \hat{\sigma}$$

## Visibility

- · Now, assuming an interferometer with a negligible bandwidth attenuation
- Visibility: data of interferometers (Fourier transform of an image)

$$\mathcal{V} \approx \int I_{\nu}(\hat{s}) \sin((\Delta \nu \tau_{\rm g})) \exp(-i2\pi \nu_{\rm c} \tau_{\rm g}) d\Omega.$$

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$$= \int A(\hat{s}) I_{\nu}(\hat{s}) \exp[-i2\pi\nu\left(\frac{\vec{b}\cdot\hat{s}}{c} - \tau_{i}\right)]$$

$$= \exp[-i2\pi\nu\left(\frac{\vec{b}\cdot\hat{s}_{0}}{c} - \tau_{i}\right)] \int A(\hat{s}) I_{\nu}(\hat{s}) d\Omega$$

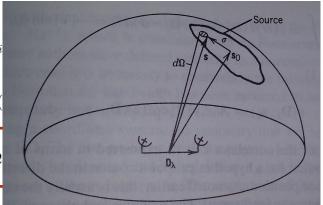
$$V = \int A(\hat{s}) I_{\nu}(\hat{s}) \exp[-i2\pi\nu \left(\frac{\vec{b}\cdot\hat{\sigma}}{c}\right)] d\Omega$$

Steering antenna with an instrumental delay

$$\tau = \tau_g - \tau_i$$

Phase center s<sub>0</sub>

$$\hat{s} = \hat{s_0} + \hat{\sigma}$$



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#### Interferometers in 3D

$$V = \int A(\hat{s}) I_{\nu}(\hat{s}) \exp[-i2\pi\nu \left(\frac{\vec{b} \cdot \hat{\sigma}}{c}\right)] d\Omega$$

$$2\pi\nu \frac{\vec{b}}{c} = 2\pi \frac{\vec{b}}{\lambda} = 2\pi(u, v, w)$$
$$\hat{\sigma} = (l, m, n)$$
$$d\Omega = \frac{dl \, dm}{\sqrt{1 - l^2 - m^2}}$$

$$V(u,v,w) = \int \int \frac{A(l,m)I(l,m)}{\sqrt{1-l^2-m^2}} \exp[-i2\pi(ul+vm+w\sqrt{1-l^2-m^2})] dl dm$$

$$\sqrt{1 - l^2 - m^2} \approx 1$$

$$V(u,v,w) = \exp(-i2\pi w) \int \int A(l,m)I(l,m) \exp[-i2\pi(ul+vm)] dl dm$$

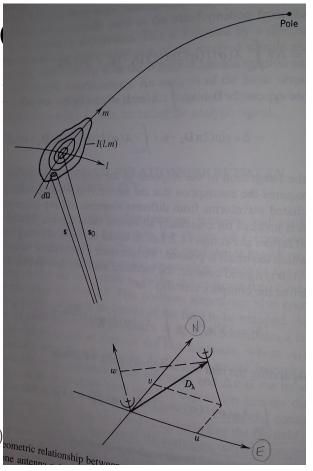
#### Interferomet

$$V = \int A(\hat{s}) I_{\nu}(\hat{s}) \exp[-i2\pi\nu \left(\frac{\vec{b} \cdot \hat{\sigma}}{c}\right)]$$

$$2\pi\nu \frac{\vec{b}}{c} = 2\pi \frac{\vec{b}}{\lambda} = 2\pi(u, v, w)$$
$$\hat{\sigma} = (l, m, n)$$
$$d\Omega = \frac{dl \, dm}{\sqrt{1 - l^2 - m^2}}$$

$$\sqrt{1 - l^2 - m^2} \approx 1$$

$$V(u,v,w) = \exp(-i2\pi w) \int \int A(l,m)I(l,m)$$



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# Visibility and Image

•(Inverse) Fourier transformation

On w = 0 plane:

$$V(u,v) = \int \int A(l,m)I(l,m) \exp[-i2\pi(ul+vm)] dl dm$$

$$V(u,v) \implies A(l,m)I(l,m)$$

$$S(u,v)V(u,v) \implies FT^{-1}[S(u,v)] * FT^{-1}[V(u,v)]$$

$$S(u,v)V(u,v) \rightleftharpoons B_D(l,m) * [A(l,m)I(l,m)]$$

## Sensitivity

A single antenna

$$\sigma_S = \frac{2kT_s}{A_e(\Delta\nu\,\tau)^{1/2}}$$

A two-element interferometer

$$\sigma_S = \frac{2^{1/2} k T_s}{A_e (\Delta \nu \tau)^{1/2}}$$

• A N-element interferometer: N(N-1)/2 independent paris

$$\sigma_S = \frac{2kT_s}{A_e [N(N-1) \Delta \nu \tau]^{1/2}}$$

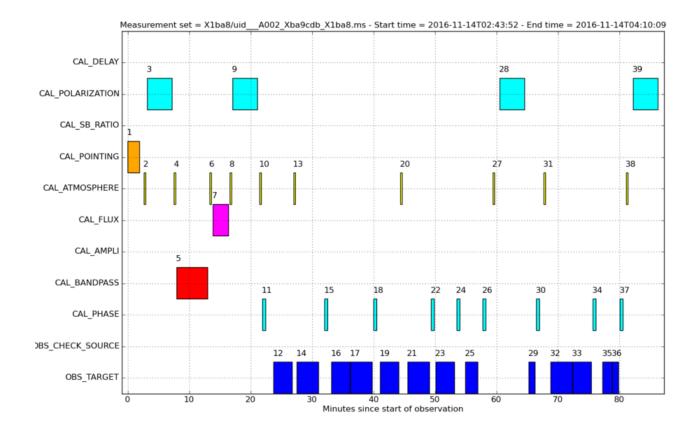
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#### Interferometric observations

- Calibrators
   Flux (also called amplitude) calibrator
   Bandpass calibrator
   Phase calibrator
- A typical sequence
   Flux cal. —> Bandpass cal. —> Phase cal. and science target cycles (e.g., 10 min period) —> Last phase cal.



**Observing Schedule** 

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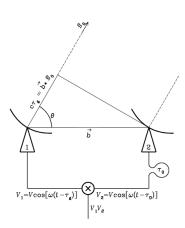
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## From raw data to image

- Calibration: to have all antennas phased up
  - Bandpass calibration
  - Flux (amplitude) calibration
  - Phase calibration



- Inverse Fourier transform
- Deconvolution
- Primary beam correction



$$S(u,v)V(u,v) \Leftrightarrow B_D(l,m)*[A(l,m)I(l,m)]$$

## Take-home messages

- Interferometry samples Fourier components of sky brightness: visibilities
- Images are made by Fourier transforming sampled visibilities
  - images are not unique
  - limited scales of detected structures due to missing visibilities

$$S(u,v)V(u,v) \implies B_D(l,m) * [A(l,m)I(l,m)]$$